# Self-consistent: 

# THE TWO SAMPLE PROBLEM WITH CENSORED DATA 

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## 1. Introduction

A medical investigator attempting to compare two different treatments for, say, prolongation of life among disease victims, often finds himself in the following situation: at time $T$, when it is necessary to end the experiment, or at least evaluate the results up to that time, a certain number of the patients in each treatment group will still be alive. His data will then be represented by two sets of numbers which might look like $x_{1}, x_{2}, x_{3}+, x_{4}, x_{5}+, x_{6}, \cdots, x_{m}$ and $y_{1}, y_{2}+, y_{3}+, y_{4}, \cdots, y_{n}$. Here $x_{1}$ and $x_{2}$ would represent actual lifetimes, while $x_{3}+$, a "censored" observation, represents a lifetime known only to exceed $x_{3}$. If all the patients in both treatment groups were treated at time 0 , then every + value would be equal to $T$, a situation that has been investigated by Halperin [1]. Frequently, however, patients enter the investigation at different times after it has begun, and the $x+$ and $y+$ values may range from 0 to $T$. Such a situation, of course, complicates the comparison of the two treatments, particularly if the mechanism censoring the $x$ values is different from that censoring the $y$ values. This may happen, for instance, if the $x$ sequence was run some time ago, so that nearly all the patients have been observed to their death times, while the $y$ sequence is begun later, and contains many censored observations.

Gehan [2] and Gilbert [3] have independently proposed the same extension of the Wilcoxon statistic as a solution to the two sample problem with censored data. In this paper the problem is discussed further, and a different test statistic is proposed, which is shown to be, in some ways, superior to the GehanGilbert statistic.

## 2. A statement of the problem and some notation

Suppose $x_{1}^{0}, x_{2}^{0}, \cdots, x_{m}^{0}$ are independent, identically distributed random variables, having $F^{0}(s)=P\left\{x_{i}^{0} \geqq s\right\}$ as their common right sided cumulative distribution function (c. d. f.). (Because of the censorship from the right, this is a more convenient function to deal with than the usual left c. d. f. Note that $F^{0}(s)$ is a left continuous, nonincreasing function of $s$, and that $F^{0}(-\infty)=1$, $F(\infty)=0$.) Likewise, let $y_{1}^{0}, y_{2}^{0}, \cdots, y_{n}^{0}$ be independent, identically distributed
random variables with common right c. d. f., $G^{0}(s)=P\left\{y_{j}^{0} \geqq s\right\}$. Both $F^{0}$ and $G^{0}$ will be assumed continuous. Our null hypothesis, which we wish to test, is

$$
\begin{equation*}
H_{0}: \quad F^{0}=G^{0} \tag{2.1}
\end{equation*}
$$

that is, the $x_{i}^{0}$ and $y_{j}^{0}$ random variables have the same distribution. What we are considering as alternatives to $H_{0}$ will become apparent as we discuss the various test statistics.

Unfortunately, we are not allowed to observe the $x_{i}^{0}$ and $y_{j}^{0}$ values directly. Rather, we are given two additional sequences of numbers, $u_{1}, u_{2}, \cdots, u_{m}$, and $v_{1}, v_{2}, \cdots, v_{n}$, and our observations consist of the minima,

$$
\begin{array}{lll}
x_{1}=\min \left(x_{1}^{0}, u_{1}\right), & x_{2}=\min \left(x_{2}^{0}, u_{2}\right), & \cdots, x_{m}=\min \left(x_{m}^{0}, u_{m}\right),  \tag{2.2}\\
y_{1}=\min \left(y_{1}^{0}, v_{1}\right), & y_{2}=\min \left(y_{2}^{0}, v_{2}\right), & \cdots, y_{n}=\min \left(y_{n}^{0}, v_{n}\right) .
\end{array}
$$

In addition, we know which of the $x_{i}$ are actually $x_{i}^{0}$, that is, uncensored observations, and which are the $u_{i}$, and likewise for the $y_{j}$. This information will be denoted by the two (random) sequences, $\delta_{1}, \delta_{2}, \cdots, \delta_{m}$ and $\epsilon_{1}, \epsilon_{2}, \cdots, \epsilon_{n}$, where

$$
\begin{align*}
\delta_{i} & =\left\{\begin{array}{l}
1 \text { if } x_{i}=x_{i}^{0} \\
0 \text { if } x_{i}<x_{i}^{0},
\end{array} \quad\left(\text { so } x_{i}=u_{i}\right) ;\right. \\
\epsilon_{0} & = \begin{cases}1 \text { if } y_{j}=y_{j}^{0} \\
0 \text { if } y_{j}<y_{j}^{0}, & \left(\text { so } y_{j}=v_{j}\right)\end{cases} \tag{2.3}
\end{align*}
$$

For the purposes of computing means, variances, efficiencies, and so forth, it is convenient to assume that the $u_{i}$ and $v_{j}$ are independent random variables themselves, with continuous right c. d. f.'s

$$
\begin{align*}
H(s) & =P\left\{u_{i} \geqq s\right\}, & i=1,2, \cdots, m \\
I(s) & =P\left\{v_{j} \geqq s\right\}, & j=1,2, \cdots, n
\end{align*}
$$

respectively. (However, the reader should keep in mind that such assumptions are not essential for the application of the various tests. This point is discussed further in section 5.) Under these assumptions, the $x_{i}$ and the $y_{j}$ are mutually independent random variables with right c. d. f.'s

$$
\begin{array}{ll}
F(s)=F^{0}(s) H(s)=P\left\{x_{i} \geqq s\right\}, & i=1,2, \cdots, m \\
G(s)=G^{0}(s) I(s)=P\left\{y_{j} \geqq s\right\}, & j=1,2, \cdots, n \tag{2.5}
\end{array}
$$

respectively. The $\delta_{i}$ and $\epsilon_{j}$ are mutually independent Bernoulli random variables, with

$$
\begin{gather*}
P\left\{\delta_{i}=1\right\}=P\left\{H \geqq F^{0}\right\}=-\int_{-\infty}^{\infty} H(s) d F^{0}(s), \\
P\left\{\epsilon_{j}=1\right\}=P\left\{I \geqq G^{0}\right\}=-\int_{-\infty}^{\infty} I(s) d G^{0}(s) . \tag{2.6}
\end{gather*}
$$

The minus sign compensates for $F^{0}$ and $G^{0}$ being decreasing functions of $s$. Throughout this paper, such notation as $P\{F \geqq G\}$ will mean "the probability that a random variable with right c. d. f. $F(s)$ is greater than an independent random variable with right c. d. f. $G(s)$," that is, $P\{F \geqq G\}=-\int_{-\infty}^{\infty} F(s) d G(s)$.

In general, the random variable $x_{i}$ will not be independent of $\delta_{i}$, and likewise for $y_{j}$ and $\epsilon_{j}$. The example in section 9 is especially simple because independence does hold in that special case.

## 3. The test statistic of Gehan and Gilbert

Let us define a "scoring function"

$$
Q_{G}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)= \begin{cases}1 \text { if } x_{i} \geqq y_{j}, & \epsilon_{j}=1,  \tag{3.1}\\ 0 \text { if } x_{i}<y_{j}, & \delta_{i}=1, \\ 1 / 2 \text { otherwise }, & \end{cases}
$$

and a statistic

$$
\begin{equation*}
W_{G}=\frac{1}{m n} \sum_{i=1}^{m} \sum_{j=1}^{n} Q_{G}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right) \tag{3.2}
\end{equation*}
$$

Because of the continuity of $F, G, H$, and $I$, the condition $x_{i} \geqq y_{j}$ could be replaced with $x_{i}>y_{j}$. However, throughout this paper, the definitions have been chosen to be consistent even when the c. d. f.'s are not continuous.

The statistic $W_{G}$ has been proposed independently by Gehan [2] and Gilbert [3] (whose names, fortunately, both begin with G) as a reasonable extension of Wilcoxon's statistic to the case of censored data. It is easily seen that $m n W_{G}$ equals the number of ( $x_{i}, y_{j}$ ) pairs where $x_{i}^{0}$ is known definitely to be larger (or as large as) $y_{j}^{0}$, plus one half the number of pairs where, on the basis of the given data, $x_{i}^{0}$ may be larger or may be smaller than $y_{j}^{0}$. It is instructive to follow Gilbert and rewrite $Q_{G}$ as

$$
Q_{G}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)=\left\{\begin{array}{l}
1 \text { if } y_{j}^{0} \leqq \min \left(x_{i}^{0}, u_{i}, v_{j}\right)  \tag{3.3}\\
0 \text { if } x_{i}^{\prime \prime}<\min \left(y_{j}^{0}, v_{j}, u_{i}\right) \\
1 / 2 \text { if } u_{i}<\min \left(x_{i}^{0}, y_{j}^{0}, v_{j}\right) \\
1 / 2 \text { if } v_{j}<\min \left(x_{i}^{0}, y_{j}^{0}, u_{i}\right)
\end{array}\right.
$$

which a simple enumeration of cases shows is equivalent to (3.1). This yields the expectation of $W_{G}$, namely

$$
\begin{align*}
E W_{G} & =E Q_{G}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)  \tag{3.4}\\
& =P\left\{F^{0} H I \geqq G^{\prime 0}\right\}+\frac{1}{2}\left[P^{\prime}\left\{F^{0} G^{0} I>H\right\}+P^{\prime}\left\{F^{0} G^{0} H>I_{j}^{\prime}\right],\right.
\end{align*}
$$

where $F^{0} H I$ is the right c. d. f. of $\min \left(x_{i}^{0}, u_{i}, v_{j}\right)$, and so forth. Under the null hypothesis, $H_{0}: F^{0}=G^{0}$, we have $I^{\prime}\left\{F^{0} H I \geqq G^{0}\right\}=P^{\prime}\left\{G^{0} H I \geqq F^{0}\right\}$, and

$$
\begin{align*}
E W_{G}=\frac{1}{2}\left[P\left\{F^{0} H I \geqq G^{0}\right\}\right. & +P^{\prime}\left\{G^{0} H I \geqq F^{0}\right\}  \tag{3.5}\\
& \left.+P^{\prime}\left\{F^{0} G^{0} I>H\right\}+P^{\{ }\left\{F^{0} G^{0} H>I\right\}\right]=\frac{1}{2}
\end{align*}
$$

independent of the distributions $H$ and $I$. (This fact was first brought to my attention by Dr. Nathan Mantel, who was kind enough to send me a preprint of his paper [4].)

Gilbert gives the following formula for the variance of $W_{G}$ under $H_{0}$

$$
\begin{align*}
\operatorname{Var}_{H_{0}}\left(W_{G}\right)= & \frac{1}{12 m n}\left[3 P\left\{H I>\left(F^{0}\right)^{2}\right\}\right.  \tag{3.6}\\
& \left.+(n-1) P\left\{H I^{2}>\left(F^{0}\right)^{3}\right\}+(m-1) P\left\{H^{2} I>\left(F^{0}\right)^{3}\right\}\right]
\end{align*}
$$

In what follows, some advantages and disadvantages of the $W_{G}$ test statistic will be discussed, particularly in comparison with the $\hat{W}$ test introduced in section 8.

## 4. Asymptotically nonparametric tests

The statistic $W_{G}$ is not nonparametric, since even under $H_{0}$, its distribution will depend on the relationship between $H, I$, and $F^{0}=G^{0}$ (this can be seen in (3.6), for instance). However, it is "asymptotically nonparametric" in the following sense: if both $m$ and $n$ go to $\infty$ in such a way that $\lim [m /(m+n)]=\lambda$, with $0<\lambda<1$, then, under $H_{0}$,

$$
\begin{equation*}
(m+n)^{1 / 2}\left(W_{G}-\frac{1}{2}\right) \underset{\mathrm{law}}{\rightarrow} N\left[0, \frac{1}{12}\left(\frac{1}{\lambda} \sigma_{1}^{2}+\frac{1}{1-\lambda} \sigma_{2}^{2}\right)\right] \tag{4.1}
\end{equation*}
$$

where

$$
\begin{align*}
& \sigma_{1}^{2}=P\left\{H I^{2}>\left(F^{0}\right)^{3}\right\} \\
& \sigma_{2}^{2}=P\left\{H^{2} I>\left(F^{0}\right)^{3}\right\} . \tag{4.2}
\end{align*}
$$

Here $N\left(\mu, \sigma^{2}\right)$ represents the normal law with mean $\mu$ and variance $\sigma^{2}$. (This is a weaker than necessary consequence of the two sample $U$ statistic theorem [5].) Moreover, $\sigma_{1}^{2}$ and $\sigma_{2}^{2}$ have consistent estimators as $m$ and $n$ go to infinity. Letting, $\hat{H}, \hat{I}$, and $\hat{F}$ be the usual (right sided) sample c. d. f.'s calculated from the $u_{i}, v_{j}$ and $x_{i}$ values, respectively, then

$$
\begin{equation*}
\hat{\sigma}_{1}^{2}=-\int_{0}^{\hat{x}} \hat{H}(s) \hat{I}^{2}(s) d\left(\frac{\hat{F}(s)}{\hat{H}(s)}\right)^{2} \tag{4.3}
\end{equation*}
$$

will estimate $\sigma_{1}^{2}$ consistently, where $\hat{x}=\max \{x: \hat{H}(x)>0\}$, and likewise for $\hat{\sigma}_{2}^{2}$.
Any asymptotically nonparametric statistic can be used to construct an asymptotically level $\alpha$ test of $H_{0}$. The only statistics considered in this paper will be those having the asymptotically nonparametric property. It must be remembered that in actual practice, the consistent estimator of the variance necessary to carry out the level $\alpha$ significance test may be more or less difficult to obtain, and this is a definite factor in comparing different test statistics.

The following well known result from parametric theory offers some insight into the asymptotically nonparametric property, and will be useful in its own right in section 9 . Suppose $f_{\theta}(x)$ is a density function depending on a $k+1$ dimensional parameter $\theta=\left(\theta^{0}, \theta^{1}, \theta^{2}, \cdots, \theta^{k}\right)$, and having information matrix $I_{\theta}=\left\{I_{i j} \mid 0 \leqq i, j \leqq k\right\}$,

$$
\begin{equation*}
I_{i j}=E_{\theta} \frac{\partial \log f_{\theta}(x)}{\partial \theta^{i}} \frac{\partial \log f_{\theta}(x)}{\partial \theta^{i}} \tag{4.4}
\end{equation*}
$$

It is desired to test $H_{0}: \theta^{0}=\theta_{0}^{0}$ on the basis of repeated independent observations $x_{1}, x_{2}, \cdots, x_{n}, \cdots$ from $f_{\theta}(x)$. Let $C$ be the class of all test statistics $t_{n}\left(x_{1}, x_{2}\right.$, $\cdots, x_{n}$ ), such that under $H_{0}$ we have

$$
\begin{equation*}
n^{1 / 2}\left(t_{n}-\mu\right) \underset{\text { law }}{\longrightarrow} N\left(0, \sigma^{2}\left(\theta_{0}\right)\right) \tag{4.5}
\end{equation*}
$$

for some constant $\mu$ not depending on $\theta_{0} \in H_{0}$. Then, under suitable regularity conditions, the efficacy of any member of $C$ is bounded above by $1 / I^{00}$, where $I^{00}$ is the upper left entry of $I_{\theta_{0}}^{-1}$. That is,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \frac{\left(\left.\frac{\partial E t_{n}}{\partial \theta^{0}}\right|_{\theta=\theta_{0}}\right)^{2}}{n \operatorname{Var}_{\theta_{0}}\left(t_{n}\right)} \leqq \frac{1}{I^{00}} \tag{4.6}
\end{equation*}
$$

for all $t_{n} \in C$. Moreover, the maximum likelihood estimate $\hat{\theta}^{0}$ attains the upper bound.

The bound above can be obtained formally from the multivariate Cramer-Rao inequality. A discussion of this type of theorem, with the suitable conditions, can be found in [6]. The class $C$, which corresponds to our asymptotically nonparametric tests, is essential to the theorem. Usually there will exist statistics outside of $C$ that do not satisfy (4.6).

A genuinely nonparametric test for $H_{0}$ is mentioned in section 5 , but is shown to be very inefficient. Both Gehan and Gilbert propose the same nonparametric test for $H_{0}$, under the additional assumption that $H=I$, that is, identical censoring distributions (namely, the permutation test based on $W_{G}$ ). However, this test is not even asymptotically nonparametric when $H \neq I$. It seems doubtful that a reasonably efficient nonparametric test for $H_{0}$ could be constructed in the general case, but the question remains open.

## 5. A test of $\boldsymbol{H}_{0}$ based on cross censorship

It is not difficult to generate whole families of asymptotically nonparametric tests of the hypothesis $H_{0}: F^{0}=G^{0}$ as an extension of Gehan and Gilbert's method. For example, let $t(x, y)$ be any bounded real valued function, and define the scoring function $Q_{t}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)$ as

$$
Q_{t}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)=\left\{\begin{align*}
t\left(x_{i}, y_{j}\right) & \text { if } x_{i} \geqq y_{j} \text { and } \epsilon_{j}=1  \tag{5.1}\\
-t\left(y_{j}, x_{i}\right) & \text { if } x_{i}<y_{j} \text { and } \delta_{i}=1, \\
0 & \text { otherwise. }
\end{align*}\right.
$$

Then under $H_{0}$ the statistic

$$
\begin{equation*}
W_{t}=\frac{1}{m n} \sum_{i=1}^{m} \sum_{j=1}^{n} Q_{t}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right) \tag{5.2}
\end{equation*}
$$

will have expectation zero, since

$$
\begin{align*}
E W_{t} & =E Q_{t}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)  \tag{5.3}\\
& =E\left[t\left(x_{i}^{0}, y_{j}^{0}\right) \mid y_{j}^{0} \leqq \min \left(x_{i}^{0}, u_{i}, v_{j}\right)\right]-E\left[t\left(y_{j}^{0}, x_{i}^{0}\right) \mid x_{i}^{0}<\min \left(y_{j}^{0}, u_{i}, v_{j}\right)\right] \\
& =0
\end{align*}
$$

under $H_{0}$ by symmetry. (If we let $t(x, y) \equiv 1$, then $2 W_{t}-1=W_{G}$.) Asymptotic normality and the existence of a consistent estimator of the large sample variance follows again from the two sample $U$ statistic theorem.

In this section, a somewhat different type of asymptotically nonparametric test statistic will be discussed briefly. Though the specific statistic derived will be shown to be inefficient relative to both $W_{G}$ and the $\hat{W}$ statistic introduced in section 8, the method of its construction is simple, and applicable in a wide variety of situations. In the sequel, it will also provide several points of comparison with the $\hat{W}$ statistic.

Suppose, for a moment, that in addition to the data $x_{i}, \delta_{i}, y_{j}, \epsilon_{j}, i=1,2$, $\cdots, m, j=1,2, \cdots, n$, we are also given the c. d. f.'s of the two censoring distributions, $H$ and $I$. This is sometimes a realistic assumption. For instance, if the entry of patients into the experiment is random in time, then $H$ and $I$ may be assumed to be uniform over the period of observation. Using a table of random numbers, draw two new sets of mutually independent random variables, say

$$
\begin{align*}
u_{1}^{*}, u_{2}^{*}, \cdots, u_{n}^{*} & \sim H \\
v_{1}^{*}, v_{2}^{*}, \cdots, v_{m}^{*} & \sim I \tag{5.4}
\end{align*}
$$

and define the "cross censored" observations

$$
\begin{array}{lll}
x_{1}^{*}=\min \left(x_{1}, v_{1}^{*}\right), & x_{2}^{*}=\min \left(x_{2}, v_{2}^{*}\right), & \cdots, x_{m}^{*}=\min \left(x_{m}, v_{n}^{*}\right), \\
y_{1}^{*}=\min \left(y_{1}, u_{1}^{*}\right), & y_{2}^{*}=\min \left(y_{2}, u_{2}^{*}\right), & \cdots, y_{n}^{*}=\min \left(y_{n}, u_{n}^{*}\right) . \tag{5.5}
\end{array}
$$

The $x_{i}^{*}$ and $y_{j}^{*}$ are mutually independent random variables, having right $\mathrm{c} . \mathrm{d} . \mathrm{f}$.'s $F^{0} H I$ and $G^{0} H I$, respectively, since $x_{i}^{*}=\min \left(x_{i}^{0}, u_{i}, v_{i}^{*}\right)$ and $y_{j}^{*}=\min \left(y_{j}^{0}, v_{j}, u_{j}^{*}\right)$. Under the null hypothesis $H_{0}, F^{0} H I=G^{0} H I$, and the usual Wilcoxon test is applicable. That is, define

$$
\begin{align*}
& Q\left(x_{i}^{*}, y_{j}^{*}\right)=\left\{\begin{array}{l}
1 \text { if } x_{i}^{*} \geqq y_{j}^{*}, \\
0 \text { if } x_{i}^{*}<y_{j}^{*} ;
\end{array}\right. \\
& W=\frac{1}{m n} \sum_{i=1}^{m} \sum_{j=1}^{n} Q\left(x_{i}^{*}, y_{j}^{*}\right) . \tag{5.6}
\end{align*}
$$

Under $H_{0}: F^{0}=G^{0}$, this $W$ will have the usual Wilcoxon distribution with

$$
\begin{equation*}
E W=\frac{1}{2}, \quad \operatorname{Var}_{I_{0}} W=\frac{1}{12} \frac{m+n+1}{m n} \tag{5.7}
\end{equation*}
$$

When $F^{0} \neq G^{0}$, the expectation is given by

$$
\begin{equation*}
E W=P\left\{F^{0} H I \geqq G^{0} H I\right\} . \tag{5.8}
\end{equation*}
$$

Since we have used a table of random numbers in the construction of $W$, we know that it is inefficient. Using the usual Rao-Blackwell method, we can get an improved statistic by considering

$$
\begin{equation*}
W_{c}=E(W \mid \text { information }), \tag{5.9}
\end{equation*}
$$

the conditional expectation being taken with respect to all of our available information: the $x_{i}, y_{i}, \delta_{i}, \epsilon_{j}$, and the functions $H$ and $I$. We will then have

$$
\begin{align*}
& E W_{c}=E W=P^{\prime}\left\{F^{0} I I I \geqq G^{0} I I I_{\}},\right.  \tag{5.10}\\
& \operatorname{Var} W_{c} \leqq \operatorname{Var} W,
\end{align*}
$$

for all choices of $F^{0}, G^{0}, H$, and $I$.
It is not difficult to express $W_{c}$ in an easily computable form. Let $F$ and $G$ be the usual (right) sample c. d. f.'s of the $x_{i}$ and $y_{j}$ observations respectively; that is, define

$$
\begin{align*}
N_{x}(s) & =\left(\text { number of } x_{i} \geqq s\right), & N_{y}(s) & \left.=\text { (number of } y_{j} \geqq s\right), \\
\hat{F}(s) & =\frac{N_{x}(s)}{m}, & \hat{G}(s) & =\frac{N_{y}(s)}{n} . \tag{5.11}
\end{align*}
$$

(Note that $\hat{F}$ represents a distribution with mass $1 / m$ at the points $x_{1}, x_{2}, \cdots, x_{m}$ and is an estimate of $F$, not $F^{0}$. Likewise, $\hat{G}$ puts mass $1 / n$ at $y_{1}, y_{2}, \cdots, y_{n}$ and estimates $G$, not $G^{0}$.)

Let $\hat{x}, \hat{y}, u^{*}$, and $v^{*}$ be independent random variables with right c. d. f.'s $\hat{F}, \hat{G}, H$, and $I$, respectively, and define $\hat{x}^{*}=\min \left(\hat{x}, v^{*}\right), \hat{y}^{*}=\min \left(\hat{y}, u^{*}\right)$. Then

$$
\begin{align*}
& P\left\{\hat{x}^{*} \geqq \hat{y}^{*}\right\}  \tag{5.12}\\
& \quad=\sum_{i=1}^{m} \sum_{j=1}^{n} P\left\{\hat{x}^{*} \geqq \hat{y}^{*} \mid \hat{x}=x_{i}, \hat{y}=y_{j}\right\} P\left\{\hat{x}=x_{i}, \hat{y}=y_{j}\right\} \\
& \quad=\frac{1}{m n} \sum_{i=1}^{m} \sum_{j=1}^{n} P\left\{x_{i}^{*} \geqq y_{j}^{*} \mid x_{i}, y_{j}\right\} \\
& =\frac{1}{m n} \sum_{i=1}^{m} \sum_{j=1}^{n} E\left[Q\left(x_{i}^{*}, y_{j}^{*}\right) \mid x_{i}, y_{j}\right] \\
& =E(W \mid \text { information })=W_{c} .
\end{align*}
$$

Since by definition $P\left\{\hat{x}^{*} \geqq \hat{y}^{*}\right\}=P\{\hat{F} I \geqq \hat{G} H\}$, we have

$$
\begin{align*}
W_{c} & =P\{\hat{F} I \geqq \hat{G} H\}  \tag{5.13}\\
& =-\int_{-\infty}^{\infty} \hat{F}(s) I(s) d[\hat{G}(s) H(s)],
\end{align*}
$$

in close analogy with the integral expression for the usual Wilcoxon statistic in the uncensored situation, which is, in our type of notation, $-\int_{-\infty}^{\infty} \hat{F}(s) d \hat{G}(s)$.

It is easy to show (by the methods used in section 8, or by the theorem on $U$ statistics) that as we let $m$ and $n$ go to infinity so that $\lim [m /(m+n)]=\lambda$, where $0<\lambda<1$, then $W_{c}$ is asymptotically normal, and under $H_{0}$,

$$
\begin{equation*}
(m+n)^{1 / 2}\left(W_{c}-\frac{1}{2}\right) \underset{\text { law }}{\rightarrow} N\left(0, \frac{1}{\lambda} \sigma_{1}^{2}+\frac{1}{1-\lambda} \sigma_{2}^{2}\right) \tag{5.14}
\end{equation*}
$$

where, if we define $F^{0} H I=G^{0} H I \equiv L$,

$$
\begin{align*}
& \sigma_{1}^{2}=\int_{0}^{1} I\left(L^{-1}(z)\right) z^{2} d z-\frac{1}{4}  \tag{5.15}\\
& \sigma_{2}^{2}=\int_{0}^{1} H\left(L^{-1}(z)\right) z^{2} d z-\frac{1}{4} .
\end{align*}
$$

Since $L(s) \leqq H(s)$ and $L(s) \leqq I(s)$ for all values of $s$, we have

$$
\begin{equation*}
\int_{0}^{1} z^{3} d z-\frac{1}{4} \leqq \sigma_{1}^{2}, \quad \sigma_{2}^{2} \leqq \int_{0}^{1} z^{2} d z-\frac{1}{4} \tag{5.16}
\end{equation*}
$$

or

$$
\begin{equation*}
0 \leqq \sigma_{1}^{2}, \quad \sigma_{2}^{2} \leqq \frac{1}{12} \tag{5.17}
\end{equation*}
$$

The upper bound is attained when there is no censoring, and coincides, of course, with the usual asymptotic variance of the Wilcoxon statistic.

If the censoring distributions $H$ and $I$ are not known to us, it is natural to replace them by their sample estimates, $\hat{H}$ and $\hat{I}$. Substituting into (5.13) yields the statistic

$$
\begin{equation*}
W_{\hat{c}}=-\int_{-\infty}^{\infty} \hat{F}(s) \hat{I}(s) d[\hat{G}(s) \hat{H}(s)] . \tag{5.18}
\end{equation*}
$$

This statistic can also be derived from permutation considerations: define

$$
Q\left(x_{i}, y_{j}, u_{k}, v_{\ell}\right)=\left\{\begin{array}{l}
1 \text { if } \min \left(x_{i}, v_{\ell}\right) \geqq \min \left(y_{j}, u_{k}\right),  \tag{5.19}\\
0 \text { if } \min \left(x_{i}, v_{\ell}\right)<\min \left(y_{j}, u_{k}\right) .
\end{array}\right.
$$

Then

$$
\begin{equation*}
W_{\hat{c}}=\frac{1}{m^{2} n^{2}} \sum_{i=1}^{m} \sum_{j=1}^{n} \sum_{k=1}^{m} \sum_{\ell=1}^{n} Q\left(x_{i}, y_{j}, u_{k}, v_{\ell}\right) . \tag{5.20}
\end{equation*}
$$

$W_{\hat{c}}$ is asymptotically normal, by the multisample $U$ statistic theorem, and has expectation $1 / 2$ under $H_{0}$. In some ways, it might be tempting to use (5.18) instead of (5.13) even if $H$ and $I$ were completely known, since given any sample, the randomness of the censoring variables is really of no interest to us. On the other hand, to compute $W_{\hat{c}}$, we must know all the $u_{i}$ and $v_{j}$ values, as opposed to $W_{G}, W_{c}$, and, as it will turn out, $\hat{W}$, where only the $u_{i}$ and $v_{j}$ corresponding to censored $x_{i}$ and $y_{j}$ are needed. Even if all the $u_{i}$ and $v_{j}$ are available, which is often not the case, this is philosophically unsatisfying, particularly from a Bayesian point of view.

As commented before, the $W_{c}$ test will be shown to have low efficiency on the case considered in section 9 . This is mainly because it ignores the difference between censored and uncensored $x_{i}$ and $y_{j}$, as can be seen in (5.13). It is easy to construct cross censorship tests which do not ignore the differences, but the author has not computed efficiencies for any such test.

## 6. Alternatives to the null hypothesis

A desirable property of any test statistic for the two sample problem is that when the null hypothesis is not true, that is when $F^{0} \neq G^{0}$, the statistic estimates some reasonable measure of the difference between the two distributions. Usually, we are not interested in a simple acceptance or rejection of the null hypothesis, but would like to make a quantitative assessment of the treatment differences. One of the virtues of the usual Wilcoxon statistic, as applied
to uncensored data, is that it estimates $P\left\{F^{0} \geqq G^{0}\right\}$, a parameter that is usually very relevant to the investigator. The asymptotic and approximate nature of the tests we are investigating intensifies the need for a test statistic that is also a reasonable estimator. And also, of course, for an asymptotically normal statistic the nature of the expectation when $F^{0} \neq G^{0}$ determines what type of alternatives to the null hypothesis the tests will tend to have the most power against.

The statistics we have discussed so far, $W_{G}, W_{c}$ and $W_{\hat{c}}$ have the unfortunate property that when $F^{0} \neq G^{0}$, their expectations depend on the censoring distributions $H$ and $I$, which play the role of nuisance parameters in our nonparametric situation. Concentrating our attention on $W_{G}$, let us write $x_{i}^{0} \gg y_{j}^{0}$ if we can infer from the available data that $x_{i}^{0} \geqq y_{j}^{0}$, which will be the case if and only if $x_{i} \geqq y_{j}$ and $\epsilon_{j}=1$. Likewise, write $y_{j}^{0} \gg x_{k}^{0}$ if $y_{j}>x_{i}$ and $\delta_{i}=1$. Equation (3.4) can then be rewritten as

$$
\begin{align*}
E W_{G} & =\frac{1}{2}\left[P\left\{F^{0} H I \geqq G^{0}\right\}-P\left\{G^{0} H I>F^{0}\right\}\right]+\frac{1}{2}  \tag{6.1}\\
& =\frac{1}{2}\left[P\left\{x_{i}^{0} \gg y_{j}^{0}\right\}-P\left\{y_{j}^{0} \gg x_{i}^{0}\right]+\frac{1}{2}\right.
\end{align*}
$$

We see that the $W_{G}$ test will always be consistent when $F^{0}$ is stochastically larger (or smaller) than $G^{0}$, for then $F^{0}(s)>G^{0}(s)$ for all $s$, and

$$
\begin{align*}
P & \left\{F^{0} H I \geqq G^{0}\right\}-P\left\{G^{0} H I>F^{0}\right\}  \tag{6.2}\\
& =-\int_{-\infty}^{\infty} F^{0}(s) H(s) I(s) d G^{0}(s)+\int_{-\infty}^{\infty} G^{0}(s) H(s) I(s) d F^{0}(s) \\
& =-\int_{-\infty}^{\infty} F^{0} H I d\left(G^{0}-F^{0}\right)+\int_{-\infty}^{\infty}\left(G^{0}-F^{0}\right) H I d F^{0} \\
& =\int_{-\infty}^{\infty}\left(G^{0}-F^{0}\right) d\left(F^{0} H I\right)+\int_{-\infty}^{\infty}\left(G^{0}-F^{0}\right) H I d F^{0}>0,
\end{align*}
$$

which implies from (6.1) that $E W_{G}>1 / 2$.
In cases where $F^{0}$ and $G^{0}$ are not stochastically comparable, the parameter $E W_{G}$ can be positive, negative, or zero, depending on the censoring distributions, and even in simple situations can yield misleading information. Consider for example, the case where the $x_{i}^{0}$ and the $u_{i}$ have independent uniform distributions over the interval ( $-1,1$ ), while the $y_{j}^{0}$ and $v_{j}$ are uniformly distributed over ( $-1 / 2,1 / 2$ ). A simple calculation shows that $P\left\{x_{i}^{0} \gg y_{j}^{0}\right\}=17 / 96$, while $P\left\{z_{j}^{0} \gg x_{i}^{0}\right\}=31 / 96$; that is, among the expected 50 per cent of the ( $x_{i}, y_{j}$ ) pairs where we know the ordering of ( $x_{i}^{0}, y_{j}^{0}$ ), nearly twice as many will favor $y_{j}^{0}$ as favor $x_{i}^{0}$. The expectation of $W_{G}$ is 0.426 in this case, indicating a strong advantage for the $y^{0}$ distribution. Such a conclusion would obviously be inappropriate in many situations.

One of the major advantages of the $\hat{W}$ statistic introduced in section 8 is that it estimates the usual Wilcoxon parameter $P\left\{F^{0} \geqq G^{0}\right\}$, independently of the censoring distributions $H$ and $I$.

## 7. Nonparametric estimates of $\boldsymbol{F}^{0}$ and $\boldsymbol{G}^{0}$

An obvious weakness in the definition of $W_{G}$ can be seen in formula (3.3) in those cases where we are not certain of the ordering between $x_{i}^{0}$ and $y_{j}^{0}$ we ascribe a probability of $1 / 2$ to both possible cases $x_{i}^{0} \geqq y_{j}^{0}, x_{i}^{0}<y_{j}^{0}$, irrespective of the relative magnitudes of $x_{i}$ and $y_{j}$. We will now discuss nonparametric estimates of $F^{0}$ and $G^{0}$ with an eye toward remedying this weakness. Our discussion will be from a point of view particularly suitable to the two sample problem.

Given $x_{1}, x_{2}, \cdots, x_{m}$ and $\delta_{1}, \delta_{2}, \cdots, \delta_{m}$, we have already introduced $\hat{F}(s)$, the sample estimate for $F(s)$, as the usual right sided empirical c. d. f. of the $x_{i}$. That is, letting

$$
\begin{equation*}
N_{x}(s)=\text { number of } x_{i} \geqq s, \tag{7.1}
\end{equation*}
$$

we define

$$
\begin{equation*}
\hat{F}(s)=\frac{N_{x}(s)}{m}, \tag{7.2}
\end{equation*}
$$

a left continuous, nonincreasing function of $s$ satisfying $\hat{F}(-\infty)=1, \hat{F}(\infty)=0$, and representing a discrete probability distribution with mass $1 / m$ at $x_{1}, x_{2}$, $\cdots, x_{m}$.
Similarly, we would like to define $\hat{F}^{0}(s)=N_{x^{0}}(s) / m$, when $N_{x^{0}}(s)$ equals the number of $x_{i}^{0} \geqq s$, but because of the censorship, the function $N_{x^{0}}(s)$ is not available to us. Since $x_{i}^{0} \geqq x_{i}$ for every $i$, we do know that $x_{i} \geqq s$ implies $x_{i}^{0} \geqq s$, so $N_{x^{0}}(s) \geqq N_{x}(s)$ for every $s$. For an $x_{i}<s$ that is uncensored, $x_{i}^{0}=x_{i}<s$, and $x_{i}^{0}$ cannot contribute to $N_{x^{0}}(s)$. The ambiguous situation is $x_{i}<s, x_{i}$ censored ( $\delta_{i}=0$ ), in which case $x_{i}^{0}$ will be equal to or greater than $s$ with conditional probability $F^{0}(s) / F^{0}\left(x_{i}\right)$. Of course we do not know $F^{0}(s)$, but given any initial estimate of it, say $\hat{F}_{1}^{0}(s)$, it seems natural to estimate the conditional probability $P\left\{x_{i}^{0} \geqq s \mid x_{i}<s, \delta_{i}=0\right\}$ by $\hat{F}_{1}^{0}(s) / \hat{F}_{1}^{0}\left(x_{i}\right)$, and define an improved estimate of $F^{0}(s)$ by

$$
\begin{align*}
& m \hat{F}_{2}^{0}(s)=N_{x}(s)+\sum_{x_{i}<s} \frac{\hat{F}_{1}^{0}(s)}{\delta_{i}=0}  \tag{7.3}\\
&=N_{x}(s)+\sum_{x_{i}<s}\left(1-\delta_{i}\right) \\
& \hat{F}_{1}(s) \\
& \hat{F}_{1}\left(x_{i}\right)
\end{align*}
$$

Iterating, we could then use $\hat{F}_{2}^{0}$ in place of $\hat{F}_{1}^{0}$ above to get another improved estimate $\hat{F}_{3}^{0}$, and so forth, and the question arises whether the sequence $\hat{F}_{1}^{0}, \hat{F}_{2}^{1}$, $\hat{F}_{3}^{0}, \cdots$ would converge to a function $\hat{F}^{0}$ which could then not be further improved by application of (7.3). Such a function would have to satisfy

$$
\begin{equation*}
m \hat{F}^{0}(s)=N_{x}(s)+\sum_{x_{i}<s}\left(1-\delta_{i}\right) \frac{\hat{F}^{0}(s)}{\hat{F}^{0}\left(x_{i}\right)} \tag{7.4}
\end{equation*}
$$

for all $s$. We shall call a function satisfying (7.4) a "self-consistent" estimate of $F^{0}(s)$, and prove the following theorem.

Theorem 7.1. Given $x_{1}, x_{2}, \cdots, x_{m}$ and $\delta_{1}, \delta_{2}, \cdots, \delta_{m}$, there is a unique function $\hat{F}^{0}(x)$ satisfying (7.4) for all values of $s$. Assume without loss of generality, that $x_{1}<x_{2}<x_{3}<\cdots<x_{m}$. Then $\hat{F}^{0}(s)$ has all the usual properties of a right c. d. f., and represents a discrete distribution with mass

$$
\begin{equation*}
\left[m-\sum_{i=1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right]^{-1} \tag{7.5}
\end{equation*}
$$

at $x_{k}$ if $x_{k}$ is uncensored, and mass

$$
\begin{equation*}
\left[m-\sum_{i=1}^{m-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right]^{-1} \tag{7.6}
\end{equation*}
$$

at $x_{m}$ uncensored or not. Here $\hat{F}^{0}(s)$ is defined iteratively by

$$
\hat{F}^{0}(s)=\left\{\begin{array}{lr}
1, & N_{x}(s)  \tag{7.7}\\
{\left[\begin{array}{lr}
\left.k-\sum_{i=1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right]
\end{array},\right.} & x_{k-1}<s \leqq x_{k}, \\
2 \leqq k \leqq m \\
0, & s>x_{m}
\end{array}\right.
$$

Corollary 7.1. The self-consistent estimate $\hat{F}^{0}(s)$ coincides with Kaplan and Meier's [7] product limit estimate

$$
\begin{equation*}
\hat{P}(s)=\prod_{i=1}^{k-1}\left(\frac{m-i}{m-i+1}\right)^{\delta_{i}}, \quad s \in\left(x_{k-1}, x_{k}\right] \tag{7.8}
\end{equation*}
$$

if we define $\hat{P}(s)=0$ for $s>x_{m}$. They have shown [7] that $\hat{P}(s)$ is the nonparametric maximum likelihood estimate of $\boldsymbol{F}^{0}(s)$.

Proof. Consider the function $\hat{F}^{0}(s)$ defined by (7.7). For $s \leqq x_{1}, \hat{F}^{0}(s)=1$ and satisfies (7.4). If $\delta_{1}=1$, we see that $\hat{F}^{0}\left(x_{1}\right)-\hat{F}^{0}\left(x_{1}+\right)=1 / m$. If $\delta_{1}=0$, $m-\left(1-\delta_{1}\right) / \hat{F}^{0}\left(x_{1}\right)=m-1$, and $\hat{F}^{0}\left(x_{1}+\right)=\hat{F}^{0}\left(x_{1}\right)=1$.

Suppose now that for some $k$, with $2 \leqq k \leqq m-1$,

$$
\begin{equation*}
m-\sum_{i=1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}>0, \quad \hat{F}^{0}\left(x_{k-1}+\right)>0 \tag{7.9}
\end{equation*}
$$

Then from (7.7)

$$
\begin{equation*}
\left[m-\sum_{i=1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right] \hat{F}^{0}(s)=N_{x}(s), \quad x_{k-1}<s \leqq x_{k} \tag{7.10}
\end{equation*}
$$

and $\hat{F}^{0}(s)$ satisfies (7.4) for $s$ in the half open interval ( $\left.x_{k-1}, x_{k}\right]$. Since $N_{x}(s)$ is constant in this interval, so is $\hat{F}^{0}(s)$, and $\hat{F}^{0}\left(x_{k}\right)=\hat{F}^{0}\left(x_{k-1}+\right)$. If $\delta_{k}=1$,

$$
\begin{align*}
m-\sum_{i=1}^{k} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)} & =m-\sum_{i=1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}>0  \tag{7.11}\\
\hat{F}^{0}\left(x_{k}+\right) & =\left[N_{x}\left(x_{k}\right)-1\right]\left[m-\sum_{1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right]>0 \tag{7.12}
\end{align*}
$$

with

$$
\begin{equation*}
\hat{F}^{0}\left(x_{k}\right)+\hat{F}^{0}\left(x_{k}+\right)=\left[m-\sum_{i=1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right]^{-1} \tag{7.13}
\end{equation*}
$$

If $\delta_{k}=0$,

$$
\begin{align*}
{\left[m-\sum_{i=1}^{k} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right] \hat{F}^{0}\left(x_{i}\right) } & =\left[m-\sum_{i=1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right] \hat{F}^{0}\left(x_{i}\right)-1  \tag{7.14}\\
& =N_{x}\left(x_{k}\right)-1=N_{x}\left(x_{k}+\right),
\end{align*}
$$

which implies that (7.11) >0 in this case. Since by (7.7)

$$
\begin{equation*}
\left[m-\sum_{i=1}^{k} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right] \hat{F}^{0}\left(x_{k}+\right)=N_{x}\left(x_{k}+\right), \tag{7.15}
\end{equation*}
$$

we have $\hat{F}^{0}\left(x_{k}+\right)=\hat{F}^{0}\left(x_{k}\right)>0$.
In either case, the argument proceeds by induction until we have verified (7.4) for $s \in\left(-\infty, x_{m-1}\right]$, and shown that $\hat{F}^{0}\left(x_{m-1}+\right)>0, m-\sum_{i=1}^{m-1}\left(1-\delta_{i}\right) / \hat{F}^{0}\left(x_{i}\right)=$ 0 . From (7.7), this verifies (7.4) for $s \in\left(x_{m-1}, x_{m}\right.$ ], while $F^{0}(s)=0$ trivially satisfies (7.4) for $s>x_{m}$. Since $\hat{F}^{0}\left(x_{m}\right)=\hat{F}^{0}\left(x_{m-1}+\right)$, the jump at $x_{m}$ equals (7.5).
Note that if $\delta_{m}=1$,

$$
\begin{equation*}
m-\sum_{i=1}^{m} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}=m-\sum_{i=1}^{m-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}>0 \tag{7.16}
\end{equation*}
$$

while if $\delta_{m}=0$,

$$
\begin{equation*}
\left[m-\sum_{1}^{m} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}\right] F_{0}\left(x_{i}\right)=N_{x}\left(x_{m}\right)-1=0, \tag{7.17}
\end{equation*}
$$

implying $m-\sum_{1}^{m}\left(1-\delta_{i}\right) / \hat{F}^{0}\left(x_{i}\right)=0$.
The argument verifying the uniqueness of $\hat{F}^{\mathrm{c}}(s)$ proceeds by induction in a manner almost identical with the above.

To prove the corollary, note that $\hat{F}^{0}(s)=\hat{P}(s)=1$, for $s \leqq x_{1}$. Suppose that $\hat{F}^{0}\left(x_{k}\right)=\widehat{P}\left(x_{k}\right)$ for some value of $k$, with $1 \leqq k \leqq m-1$. If $\delta_{k}=0$, then by the proof above and by definitions (7.7) and (7.8) $\hat{F}^{0}\left(x_{k}+\right)=\hat{F}^{0}\left(x_{k}\right)=\widehat{P}\left(x_{k}\right)=$ $\widehat{P}\left(x_{k}+\right)$, implying that $\hat{F}^{0}(s)=\widehat{P}(s)$ for $s \in\left(x_{k}, x_{k+1}\right]$.

If $\delta_{k}=1$, then

$$
\begin{align*}
\hat{F}\left(x_{k}+\right) & =\frac{N_{x}\left(x_{k}+\right)}{m-\sum_{1}^{k} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}}=\frac{N_{x}\left(x_{k}+\right)}{N_{x}\left(x_{k}\right)} \frac{N_{x}\left(x_{k}\right)}{m-\sum_{1}^{k-1} \frac{1-\delta_{i}}{\hat{F}^{0}\left(x_{i}\right)}}  \tag{7.18}\\
& =\frac{m-k}{m-k+1} \hat{P}\left(x_{k}\right)=\hat{P}\left(x_{k}+\right),
\end{align*}
$$

implying again that $\hat{F}^{0}(s)=\hat{P}(s)$ for $s \in\left(x_{k}, x_{k+1}\right]$. The proof of the corollary is completed by induction.

The self-consistent (product limit) estimate is also given by the following simple construction; place probability mass $1 / m$ at each of the points $x_{1}<x_{2}<$ $x_{3}<\cdots<x_{m}$, (that is, construct the distribution with $\hat{F}(s)$ as c. d. f.); if $x_{i 1}$ is the smallest $x_{i}$ that is censored, remove the mass at $x_{i 1}$ and redistribute it equally among the $m-i_{1}$ points to the right of it, $x_{i+1}, x_{i+2}, \cdots, x_{m}$. If $x_{i 2}$ is the smallest censored value among $x_{i_{1}+1}, x_{i+2}, \cdots, x_{m}$, redistribute its mass,
which will be $1 / m+1 /\left(m-i_{1}\right)$, among the $m-m_{2}$ points to its right, $x_{i_{2}+1}$, $x_{i 2}+2, \cdots, x_{m}$; continue in this way until you reach $x_{m}$. The resulting distribution has mass

$$
\begin{equation*}
\frac{1}{m} \prod_{1}^{k-1}\left(\frac{m-i+1}{m-i}\right)^{1-\delta_{i}} \tag{7.19}
\end{equation*}
$$

at $x_{k}$ uncensored, and at $x_{m}$ censored or not, which is easily computed to agree with $\hat{F}^{0}(s)$ from equation (7.8). This construction sheds some light on the special nature of the largest observation, which the self-consistent estimator always treats as uncensored, irrespective of $\delta_{m}$.

In addition to the maximum likelihood property of $\hat{F}^{0}$, Kaplan and Meier derive several other results which will be of use to us in the next section.
(a) $\hat{F}^{0}(s)$ is a nearly unbiased estimator of $F^{0}(s)$. Specifically,

$$
\begin{equation*}
1 \geqq \frac{E \hat{F}^{0}(s)}{F^{0}(s)} \geqq 1-e^{-E N_{z}(s)} \tag{7.20}
\end{equation*}
$$

or equivalently,

$$
\begin{equation*}
0 \leqq F^{0}(s)-E \hat{F}^{0}(s) \leqq F^{0}(s) e^{-E N_{x}(s)} \tag{7.21}
\end{equation*}
$$

Since $E N_{x}(s)=m F(s)$, the bias of $\hat{F}^{0}(s)$ declines exponentially with sample size whenever $F(s)=F^{0}(s) H(s)>0$ (that is, whenever it is possible and necessary to estimate $F^{0}(s)$ nonparametrically). In the sequel, we will treat $\hat{F}^{0}(s)$ as if it were unbiased, since the exponential decline of the bias term easily overwhelms the $m^{1 / 2}$ magnification needed for the large sample theory.

Harking back, briefly, to the point raised in section 2, equation (7.20) also holds when the $u_{i}$ are a fixed set of constants, say $u_{1}<u_{2}<u_{3}<\cdots<u_{m}$, in which case it is simple to show that the relative bias $E \hat{F}^{0}(s) / F^{0}(s)$ is a constant within any interval ( $u_{k-1}, u_{k}$ ].
(b) $\hat{F}^{0}(s)$ is a consistent estimator of $F^{0}(s)$, as $m$ goes to infinity.
(c) $m^{1 / 2}\left[\hat{F}^{0}(s)-F^{0}(s)\right]$, considered as a stochastic process in $s$, approaches in the limit for large $m$, a normal process with mean 0 and covariance kernel

$$
\begin{equation*}
\Gamma(s, t)=F^{0}(s) F^{0}(t) \int_{-\infty}^{s} \frac{-d F^{0}(z)}{F(z) F^{0}(z)}, \quad s \leqq t \tag{7.22}
\end{equation*}
$$

(The limiting normality is not discussed by Kaplan and Meier, but can be derived easily from (7.7) by standard methods.)

The covariance kernel (7.9) represents a distorted Wiener process of the type discussed by Doob in his famous paper on the Kolmogorov-Smirnov statistic [8]. Suppose, for convenience, that $F^{0}(s)=1$, so that we are dealing with positive random variables. Define

$$
\begin{equation*}
a(s)=\int_{0}^{s} \frac{-d F^{0}(z)}{F(z) F^{0}(z)} \tag{7.23}
\end{equation*}
$$

an increasing function of $s$ for $s$ less than $M$, any value such that $F^{0}(M)>0$, and let $a^{-1}(s)$ denote its inverse function. Then for $0 \leqq s \leqq M$, the process

$$
\begin{equation*}
Y(s)=m^{1 / 2} \frac{\hat{F}^{0}\left[a^{-1}(s)\right]-F^{0}\left[a^{-1}(s)\right]}{F^{0}\left[a^{-1}(s)\right]} \tag{7.24}
\end{equation*}
$$

approaches a standard Wiener process as $m$ goes to infinity. That is, $Y$ approaches a normal process with mean zero and covariance kernel $\Gamma(s, t)=$ $\min (s, t)$ for $0 \leqq s, t \leqq M$.

## 8. The statistic $\hat{W}$

We now use $\hat{F}^{0}(s)$ and $\hat{G}^{0}(s)$, the self-consistent estimates of $F^{0}$ and $\hat{G}^{0}$, respectively, to modify the statistic $W_{G}$ along the lines suggested at the beginning of section 7. As mentioned previously, the self-consistent estimates treat the largest observation of each group as if it were uncensored, and we will assume that this is actually the situation, to avoid a host of annoying special cases. That is, we will assume the $\delta_{i}$ and $e_{j}$ corresponding to the largest $x_{i}$ and largest $y_{j}$ respectively are both equal to 1 .

Define the scoring function $\hat{Q}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)$ to be

$$
\begin{equation*}
\widehat{Q}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)=P\left\{x_{i}^{0} \geqq y_{j}^{0} \mid x_{i}, y_{j}, \delta_{i}, \epsilon_{j}, \hat{F}^{0}, \hat{G}_{j}^{0}\right\} \tag{8.1}
\end{equation*}
$$

where the conditional expectation is interpreted as if $x_{i}^{0}$ and $y_{j}^{0}$ were actually drawn from $\hat{F}^{0}$ and $\hat{G}^{0}$, respectively. Thus, if $x_{i} \geqq y_{j}$ and $\epsilon_{j}=1$, then $\hat{Q}\left(x_{i}, y_{j}\right.$, $\left.\delta_{i}, \epsilon_{j}\right)=1$ as before. However, if $x_{i} \geqq y_{j}$ and $\epsilon_{j}=0, \delta_{i}=1$, we no longer score $1 / 2$ to indicate equal probability for $x_{i}^{0} \geqq y_{j}^{0}$ and $x_{i}^{0}<y_{j}^{0}$; rather $\hat{Q}\left(x_{i}, y_{j}, \delta_{i}\right.$, $\left.\epsilon_{j}\right)=1-\hat{G}^{0}\left(x_{i}\right) / \hat{G}^{0}\left(y_{j}\right)$ in this case, the conditional probability under $\hat{G}^{0}$ that $y_{j}^{0} \geqq y_{j}$ is less than $x_{i}^{0}=x_{i}$. Table I lists the value of $Q\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)$ in all eight possible different cases.

TABLE I
Valles of $Q\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)$

| $\left(\delta_{i}, \epsilon_{j}\right)$ | $x_{i} \geqq y_{j}$ | $x_{i}<y_{j}$ |
| :---: | :---: | :---: |
| $(1,1)$ | 1 | 0 |
| $(0,1)$ | 1 | $\frac{\hat{F}^{0}\left(y_{j}\right)}{\hat{F}^{0}\left(x_{i}\right)}$ |
| $(1,0)$ | $1-\frac{\hat{G}^{0}\left(x_{i}\right)}{\hat{G}^{0}\left(y_{j}\right)}$ | 0 |
| $(0,0)$ | $1-\frac{\hat{G}^{0}\left(x_{i}\right)}{\hat{G}^{0}\left(y_{j}\right)}-\int_{x_{i}}^{\infty} \frac{F^{0}(s) d G^{0}(s)}{F^{0}\left(x_{i}\right) G^{0}\left(y_{j}\right)}$ | $-\int_{\nu_{i}}^{\infty} \frac{\hat{F}^{0}(s) \alpha \hat{G}^{0}(s)}{\hat{F}^{0}\left(x_{i}\right) \hat{G}^{0}\left(y_{j}\right)}$ |

The statistic $\hat{W}$ is now defined in the usual way in terms of $\hat{Q}\left(x_{i}, y_{j}, \delta_{i}, \boldsymbol{\epsilon}_{j}\right)$

$$
\begin{equation*}
\hat{W}=\frac{1}{m n} \sum_{i=1}^{m} \sum_{j=1}^{n} \hat{Q}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right) \tag{8.2}
\end{equation*}
$$

Theorem 8.1. $\hat{W}=-\int_{-\infty}^{\infty} \hat{F}^{0}(s) d \hat{G}^{0}(s)=P\left\{\hat{F}^{0} \geqq \hat{G}^{0}\right\}$, and is the maximum likelihood estimate of $P\left\{\hat{F}^{0} \geqq \hat{G}^{0}\right\}$.

Proof. To simplify notation, let $P\left\{x_{i}^{0} \geqq y_{j}^{0}\right\}$ be the conditional expectation defined at (8.1) and below, and listed in table I. We shall also need $\hat{g}^{0}\left(y_{j}\right)=$ $\hat{G}^{0}\left(y_{j}\right)-\hat{G}^{0}\left(y_{j}+\right)$, the probability mass function corresponding to the discrete distribution $\hat{G}^{0}(s)$. From theorem 7.1

$$
\begin{equation*}
\hat{g}^{0}\left(y_{j}\right)=\frac{\epsilon_{j}}{n-\sum_{y_{\ell}<y_{i}} \frac{1-\epsilon \ell}{\hat{G}^{0}\left(y_{\ell}\right)}} \tag{8.3}
\end{equation*}
$$

for $j=1,2,3, \cdots, n$, which can be written as

$$
\begin{equation*}
n \hat{g}^{0}\left(y_{j}\right)=1+\sum_{y_{\ell}<y_{i}} \frac{1-\epsilon_{\ell}}{\hat{G}^{0}\left(y_{\ell}\right)} \hat{g}^{0}\left(y_{j}\right), \quad \epsilon_{j}=1 . \tag{8.4}
\end{equation*}
$$

If $\epsilon_{j}=1$, then reading from the table,

$$
\begin{align*}
\sum_{i=1}^{m} \hat{P}\left\{x_{i}^{0} \geqq y_{j}^{0}\right\} & =N_{x}\left(y_{j}\right)+\sum_{x_{i}<y_{j}}\left(i-\delta_{i}\right) \frac{\hat{F}^{0}\left(y_{j}\right)}{\hat{F}^{0}\left(x_{i}\right)}  \tag{8.5}\\
& =m \hat{F}^{0}\left(y_{j}\right)
\end{align*}
$$

by the self-consistency property (7.4) of $\hat{F}^{0}$.
If $\epsilon_{j}=0$, then

$$
\begin{equation*}
\hat{P}\left\{x_{i}^{0} \geqq y_{j}^{0}\right\}=\sum_{y_{\ell} \geqq y_{i}} \frac{\hat{g}^{0}\left(y_{\ell}\right)}{\hat{G}^{0}\left(y_{j}\right)} \hat{P}\left\{x_{i}^{0} \geqq y_{\ell}^{0}\right\}, \tag{8.6}
\end{equation*}
$$

so

$$
\begin{align*}
\sum_{i=1}^{m} \hat{P}\left\{x_{i}^{0} \geqq y_{j}^{0}\right\} & =\sum_{i=1}^{m} \sum_{y_{\ell} \geqq y_{i}} \frac{g^{0}\left(y_{\ell}\right)}{\hat{G}^{0}\left(y_{j}\right)} \hat{P}\left\{x_{i}^{0} \geqq y_{\ell}^{0}\right\}  \tag{8.7}\\
& =\sum_{y_{l} \geqq y_{i}} \frac{\hat{g}^{0}\left(y_{\ell}\right)}{\hat{G}^{0}\left(y_{j}\right)}\left[\sum_{i=1}^{m} \hat{P}\left\{x_{i}^{0} \geqq y_{\ell}^{0}\right\}\right]
\end{align*}
$$

Remembering that $g^{0}\left(y_{\ell}\right)$ is nonzero only for uncensored values of $y_{\ell}$, equation (8.5) reduces this last sum to

$$
\begin{equation*}
\sum_{i=1}^{m} \hat{P}\left\{x_{i}^{0} \geqq y_{j}^{0}\right\}=m \sum_{y_{\ell} \geqq y_{j}} \frac{\hat{g}^{0}\left(y_{\ell}\right)}{\hat{G}^{0}\left(y_{j}\right)} \hat{F}^{0}\left(y_{\ell}\right) \tag{8.8}
\end{equation*}
$$

Combining (8.5) and (8.8) yields

$$
\begin{align*}
\hat{W} & =\frac{1}{m n} \sum_{j=1}^{n} \sum_{i=1}^{m} \hat{P}\left\{x_{i}^{0} \geqq y_{j}^{0}\right\}  \tag{8.9}\\
& =\frac{1}{n}\left[\sum_{\epsilon_{i}=1} \hat{F}^{0}\left(y_{j}\right)+\sum_{\epsilon_{i}=0} \sum_{y_{\ell} \geq y_{i}} \frac{\hat{g}^{0}\left(y_{\ell}\right)}{\hat{G}^{0}\left(y_{j}\right)} \hat{F}^{0}\left(y_{\ell}\right)\right] \\
& =\frac{1}{n} \sum_{\epsilon_{i}=1} \hat{F}^{0}\left(y_{j}\right)\left[1+\sum_{y_{\ell}<y_{i}} \frac{1-\epsilon_{\ell}}{\hat{G}^{0}\left(y_{\ell}\right)} \hat{g}^{0}\left(y_{j}\right)\right] \\
& =\sum_{\epsilon_{i}=1} \hat{F}^{0}\left(y_{j}\right) \hat{g}^{0}\left(y_{j}\right)
\end{align*}
$$

by equation (8.4). Thus,

$$
\begin{equation*}
\hat{W}=-\int_{-\infty}^{\infty} \hat{F}^{0}(s) d \hat{G}^{0}(s)=P\left\{\hat{F}^{0} \geqq \hat{G}^{0}\right\} \tag{8.10}
\end{equation*}
$$

as was to be proved, and the second statement of the theorem follows from the corollary to theorem 7.1, and the usual invariance property of maximum likelihood estimates.
It should be mentioned that other consistent estimates of $F^{0}$ and $G^{0}$ exist [7], which conceivably could be used in place of $\hat{F}$ and $\hat{G}$ to define the scoring function, as was done in (8.1). However, the uniqueness of the self-consistent estimate insures that the resulting statistic will not be expressible in the form given in theorem 8.1.

Theorem 8.2. Let $m$ and $n$ go to infinity in such a way that $\lim m /(m+n)=$ $\lambda$, with $0<\lambda<1$. Then

$$
\begin{equation*}
(m+n)^{1 / 2}\left[\hat{W}-P\left\{F^{0} \geqq G^{0}\right\}\right] \underset{\operatorname{law}}{\rightarrow} N\left(0, \frac{1}{\lambda} \sigma_{1}^{2}+\frac{1}{1-\lambda} \sigma_{2}^{2}\right) \tag{8.11}
\end{equation*}
$$

where under $H_{0}$,

$$
\begin{align*}
& \sigma_{1}^{2}=\frac{1}{4} \int_{0}^{1} \frac{z^{2} d z}{H\left[F^{0^{-1}}(z)\right]}=\frac{1}{4} \int_{0}^{1} \frac{z^{3} d z}{F\left[F^{\left.0^{-1}(z)\right]}\right.} \\
& \sigma_{2}^{2}=\frac{1}{4} \int_{0}^{1} \frac{z^{2} d z}{I\left[G^{\left.0^{-1}(z)\right]}\right.}=\frac{1}{4} \int_{0}^{1} \frac{z^{3} d z}{G\left[G^{-1}(z)\right]} \tag{8.12}
\end{align*}
$$

Here $F^{0^{-1}}$ and $G^{0-1}$ are the inverse functions of $F^{0}$ and $G^{0}$, respectively, and are identical under $H_{0}$.

Proof. Only a heuristic argument will be presented here. This argument is somewhat similar to the proof of the Chernoff-Savage theorem [9], and a rigorous proof can be developed along the lines suggested in that paper.

Write

$$
\begin{align*}
-\hat{W}= & \int_{-\infty}^{\infty} \hat{F}^{0}(s) d \hat{G}^{0}(s)  \tag{8.13}\\
= & \int_{-\infty}^{\infty} F^{0} d G^{0}+\int_{-\infty}^{\infty}\left(\hat{F}^{0}-F^{0}\right) d G^{0}+\int_{-\infty}^{\infty} F^{0} d\left(\hat{G}^{0}-\hat{G}\right) \\
& +\int_{-\infty}^{\infty}\left(\hat{F}^{0}-F^{0}\right) d\left(\hat{G}^{0}-\hat{G}\right),
\end{align*}
$$

and integrate the third term by parts, yielding

$$
\begin{align*}
-\hat{W}= & \int_{-\infty}^{\infty} F^{0} d G^{0}+\int_{-\infty}^{\infty}\left(\hat{F}^{0}-F^{0}\right) d G^{0}-\int_{-\infty}^{\infty}\left(\hat{G}^{0}-G^{0}\right) d F^{0}  \tag{8.14}\\
& +\int_{-\infty}^{\infty}\left(\hat{F}^{0}-F^{0}\right) d\left(\hat{G}^{0}-G^{0}\right)
\end{align*}
$$

Of these four terms, the first is a constant, while the fourth is asymptotically negligible;

$$
\begin{align*}
\int_{-\infty}^{\infty}\left(\hat{F}^{0}\right. & \left.-F^{0}\right) d\left(\hat{G}^{0}-G^{0}\right)  \tag{8.15}\\
& =\frac{1}{(m n)^{1 / 2}} \int_{-\infty}^{\infty} m^{1 / 2}\left(\hat{F}^{0}-F^{0}\right) d n^{1 / 2}\left(\hat{G}^{0}-G^{0}\right) \\
& =o_{P}\left[\frac{1}{(m+n)^{1 / 2}}\right]
\end{align*}
$$

by property $c$ of section 7 . (The equation $x_{m, n}=o_{P}\left[1 /(m+n)^{1 / 2}\right]$ means $(m+n)^{1 / 2} x_{m, n} \xrightarrow[\text { prob }]{ } 0$ as $m, n$ go to infinity.)

Consider the second term in (8.14). By property $c$ of section 7 and equation (7.18), $\int_{-\infty}^{\infty} m^{1 / 2}\left[\hat{F}^{0}(s)-F^{0}(s)\right] d G^{0}(s)$ approaches a normal variate with mean zero and variance

$$
\begin{align*}
& \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \Gamma(s, t) d G^{0}(s) d G^{0}(t)  \tag{8.16}\\
& \quad=-2 \int_{-\infty}^{\infty} \int_{s}^{\infty} \int_{-\infty}^{s} \frac{F^{0}(s) F^{0}(t)}{F(z) F^{0}(z)} d F^{0}(z) d G^{0}(t) d G^{0}(s)
\end{align*}
$$

Now under the null hypothesis, $G^{0}=F^{0}$, this last expression becomes

$$
\begin{equation*}
-2 \int_{-\infty}^{\infty} \int_{s}^{\infty} \int_{-\infty}^{s} \frac{F^{0}(s) F^{0}(t)}{F(z) F^{0}(z)} d F^{0}(z) d F^{0}(t) d F^{0}(s) \tag{8.17}
\end{equation*}
$$

and a change of variables to $F^{0}(z), F^{0}(t)$ and $F^{0}(s)$ yields

$$
\begin{align*}
2 \int_{0}^{1} \int_{0}^{s} & \int_{s}^{1} \frac{s t}{z F\left[F^{0^{-1}}(z)\right]} d z d t d s  \tag{8.18}\\
& =2 \int_{0}^{1} \int_{0}^{z} \int_{0}^{s} \frac{s t}{z F\left[F^{\left.0^{-1}(z)\right]}\right.} d t d s d z \\
& =\frac{1}{4} \int_{0}^{1} \frac{z^{3} d z}{F\left[F^{\left.0^{-1}(z)\right]}\right.}=\frac{1}{4} \int_{0}^{1} \frac{z^{2} d z}{H\left[F^{\left.0^{-1}(z)\right]}\right.}=\sigma_{1}^{2}
\end{align*}
$$

The last equality follows from (2.5)

$$
\begin{equation*}
F\left[F^{0^{-1}}(z)\right]=H\left[F^{0^{-1}}(z)\right] F^{0}\left[F^{0^{-1}}(z)\right]=z H\left[F^{0^{-1}}(z)\right] . \tag{8.19}
\end{equation*}
$$

A similar argument gives

$$
\begin{equation*}
\sigma_{2}^{2}=\frac{1}{4} \int_{0}^{1} \frac{z^{2} d z}{\bar{I}\left[G^{0^{-1}}(z)\right]} \tag{8.20}
\end{equation*}
$$

as the limiting variance of the third term in (8.13) under $H_{0}$. Since the second and third terms of that expression are independent random variables, this completes the heuristic argument.

The expression (8.11) for $\sigma_{1}^{2}$ fails to converge if $H(z)=O\left\{\left[F^{0}(z)\right]^{3}\right\}$, as $z$ approaches 0 , and likewise $\sigma_{2}^{2}$ will not converge if $I(z)=O\left\{\left[G^{0}(z)\right]^{3}\right\}$. In these cases, the variance of $\hat{W}$ does not diminish at rate $1 /(m+n)$. This situation is illustrated in the next section, and a possible remedy suggested in section 10.

In these cases where $\sigma_{1}^{2}$ and $\sigma_{2}^{2}$ are finite, they have obvious consistent estimators in terms of equation (8.11). The second form given for each integral will often be the most convenient to compute with, since $\hat{F}^{0}(z) \geqq \hat{F}(z)$ for all $z$, and the function $\hat{F}(z)$ can be computed directly from the observed $x_{i}$. (To compute $\hat{H}$, for instance, requires knowing all the $u_{i}$ values, not just those where $x_{i}=$ $u_{i}$. As mentioned before, these may not be available, and in any case are not required to compute $\hat{W}$.)

## 9. Asymptotic relation efficiencies of the various tests in the exponential case

In this section we will compute the Pitman efficiency (A. R. E.) of $\hat{W}, W_{G}$, and $W_{c}$ relative to the best parametric test, in the special case where all the random variables involved are exponentially distributed. That is, we assume

$$
\begin{align*}
& F^{0}(s)=\left\{\begin{array}{ll}
e^{-\phi \delta}, & s \geqq 0, \\
1, & s<0,
\end{array} \quad G^{0}(s)= \begin{cases}e^{-\theta \phi s}, & s \geqq 0, \\
1, & s<0,\end{cases} \right. \\
& H(s)=\left\{\begin{array}{ll}
e^{-s}, & s \geqq 0, \\
1, & s<0,
\end{array} \quad I(s)= \begin{cases}e^{-\alpha s}, & s \geqq 0, \\
1, & s<0,\end{cases} \right. \tag{9.1}
\end{align*}
$$

where, for the purposes of the parametric test, $\alpha$ is a known positive parameter, while $\theta$ and $\phi$ are unknown. This example with $\alpha=1$ was investigated by Gilbert. Gehan evaluates the more realistic case where $H(s)=I(s)=$ a uniform distribution over [ $0, T$ ]. Our null hypothesis is $H_{0}: \theta=1$. The observed random variables $x_{i}$ and $y_{j}$ will have right c . d. f.'s,

$$
F(s)=\left\{\begin{array}{ll}
e^{-(\phi+1) s}, & s \geqq 0,  \tag{9.2}\\
1, & s<0,
\end{array} \quad G(s)= \begin{cases}e^{-(\theta \phi+\alpha) s}, & s \geqq 0, \\
1, & s<0,\end{cases}\right.
$$

respectively. The $\delta_{i}$ and $\epsilon_{j}$ are Bernoulli random variables, with

$$
\begin{equation*}
P\left\{\delta_{i}=1\right\}=\frac{\phi}{\phi+1}, \quad P\left\{\epsilon_{j}=1\right\}=\frac{\theta \phi}{\theta \phi+\alpha} \tag{9.3}
\end{equation*}
$$

In this case, $x_{i}$ and $\delta_{i}$ are independent, as are $y_{j}$ and $\epsilon_{j}$. (I am grateful to Dr. J. Sethuraman, for first bringing this useful fact of the independence of $x_{i}$ and $\delta_{i}$ to my attention.) To simplify matters further, we will let $m=n$, so the sample sizes remain equal as $n$ goes to infinity.

The efficacy $\operatorname{Eff}\left(T_{n}\right)$ of any test statistic $T_{n}$ for $H_{0}$ is defined to be

$$
\begin{equation*}
\operatorname{Eff}\left(T^{\prime}\right)=\frac{\left(\left.\frac{\partial E T_{n}}{\partial \theta}\right|_{\theta=1}\right)^{2}}{2 n \operatorname{Var}_{\theta=1, \phi} T} \tag{9.4}
\end{equation*}
$$

From the discussion in section 4, we know that the maximum likelihood estimate of $\theta$, say $M$, achieves the greatest efficacy among all computable test statistics, the class we called $C$. That efficacy is $1 / I^{00}$. In our case, assuming $\theta, \varphi$ unknown, but $\alpha$ known,

$$
\begin{equation*}
\operatorname{Eff}(M)=\frac{1}{4} \frac{\phi}{\phi+\frac{\alpha+1}{2}} \tag{9.5}
\end{equation*}
$$

at $\theta=1$.
From (4.2) and (8.12), the efficacies of $W_{G}$ and $\hat{W}$ at $\theta=1$ are

$$
\begin{equation*}
\operatorname{Iff}\left(W_{G}\right)=\frac{3}{16} \frac{\phi\left(\phi+\frac{2 \alpha+1}{3}\right)\left(\phi+\frac{\alpha+2}{3}\right)}{\left(\phi+\frac{\alpha+1}{2}\right)^{3}} \tag{9.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{Eff}(\hat{W})=\frac{3}{16} \frac{\left(\phi-\frac{1}{3}\right)\left(\phi-\frac{\alpha}{3}\right)}{\phi\left(\phi-\frac{\alpha+1}{6}\right)} \tag{9.7}
\end{equation*}
$$

Formula (9.7) holds only for $\phi>\max (1 / 3, \alpha / 3)$. For $\phi \leqq \max (1 / 3, \alpha / 3)$, the situation described at the end of section 8 prevails, and $\hat{W}$ has efficacy 0 .

The Pitman efficiency of $W_{G}$ relative to $M$, the best parametric test, is by definition

$$
\begin{align*}
P_{W_{G} / M} & =\frac{\operatorname{Eff}\left(W_{G}\right)}{\operatorname{Eff}(M)}  \tag{9.8}\\
& =\frac{3}{4} \frac{\left(\phi+\frac{2 \alpha+1}{3}\right)\left(\phi+\frac{\alpha+2}{3}\right)}{\left(\phi+\frac{\alpha+1}{2}\right)^{2}}
\end{align*}
$$

When $\alpha=1$, that is, when $H(s)=I(s)=e^{-s}$ for $s \geqq 0$, then $P_{W_{G} / M}=3 / 4$ for all values of $\phi$, agreeing with Gilbert's result. For all other values of $\alpha$ and $\phi$,

$$
\begin{equation*}
\frac{8}{9}\left(\frac{3}{4}\right)<P_{W_{\sigma} / M}<\frac{3}{4} \tag{9.9}
\end{equation*}
$$

with the lower bound achieved at the extreme points $\phi=0, \alpha=0$ and $\phi=0$, $\alpha=\infty$.

For the $\hat{W}$ statistic we have Pitman efficiency

$$
\begin{align*}
& P_{\hat{W} / M}=\frac{\operatorname{Eff}(\hat{W})}{\operatorname{Eff}(M)}  \tag{9.10}\\
& = \begin{cases}\frac{3}{4} \frac{\left(\phi-\frac{1}{3}\right)\left(\phi-\frac{\alpha}{3}\right)\left(\phi+\frac{\alpha+1}{2}\right)}{\phi^{2}\left(\phi-\frac{\alpha+1}{6}\right)} & \text { for } \phi>\max (1 / 3, \alpha / 3) \\
0 & \text { for } \phi \leqq \max (1 / 3, \alpha / 3)\end{cases}
\end{align*}
$$

Let us consider, the convenience, the case where $\alpha \leqq 1$. Then for $\phi \geqq 1 / 2$, we have $P_{\hat{W} / M} \geqq 3 / 4$. Another way of saying this is that for exponential observations and exponential censoring variables, the $W$ test is more efficient than the $W_{G}$ test as long as not more than $2 / 3$ of either sample consists of
censored observations (for when $\phi=1 / 2$, an expected $1 /(\phi+1)=2 / 3$ percentage of the $x_{i}$ and $\alpha /(\phi+\alpha) \leqq 2 / 3$ percentage of the $y_{j}$ will be censored under $H_{0}: \theta=1$ ). That the increase in efficiency can be quite substantial is shown in table II.

TABLE II
PWg/M in the Exponential Case

|  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |

The case of very large $\phi$ corresponds to a very low rate of censoring $1 /(1+\phi)$, in which case both $W_{G}$ and $W$ become equivalent to the ordinary Wilcoxon test, while the $F$ test based on $\sum_{1}^{n} x_{i} / \sum_{1}^{n} y_{j}$ corresponds to $M$. This accounts for the constant top row of the table. The same remark applies to the statistic $W_{c}$ discussed in section 5, which by (5.14) has Pitman efficiency

$$
\begin{equation*}
P_{W_{\mathrm{o}}} / M=\frac{3}{4} \frac{\phi\left(\phi+\frac{5}{3}\right)}{(\phi+2)^{2}}, \tag{9.11}
\end{equation*}
$$

when $\alpha=1$. This is quite low for reasonable values of $\phi$, not attaining even $1 / 2$ until $\phi$ is greater than 4.7.

The last column of the table is for $\alpha=0$, that is, the case where the $y_{j}^{0}$ values are uncensored.

## 10. Truncating the $\hat{W}$ statistic

The rapid loss of asymptotic efficiency of the $\hat{W}$ test when $\phi$ drops below $1 / 2$ in the example treated in section 9 can be alleviated somewhat by considering truncated modifications of the $\hat{W}$ statistic. We will consider here, briefly, such modifications, first in general, and then as applied to the exponential case as given by (9.1).

Let $D(s)$ be any continuous right c. d. f., and define

$$
\begin{align*}
& \tilde{x}_{i}^{0}=\min \left(x_{i}^{0}, z_{i}\right), \\
& \tilde{y}_{j}^{0}=\min \left(y_{j}^{0}, z_{m+j}\right) . \tag{10.1}
\end{align*}
$$

Here the $z$ are mutually independent random variables, identically distributed according to $D(s)$. Following our previous notation, (2.2), (2.3), let

$$
\begin{array}{ll}
x_{i}=\min \left(x_{i}^{0}, u_{i}\right), & \tilde{y}_{j}=\min \left(\tilde{y}_{j}^{0}, v_{j}\right), \\
\delta_{i}= \begin{cases}1 \text { if } \tilde{x}_{i}=x_{i}^{0}, \\
0 \text { if } \tilde{x}_{i}<x_{i}^{0},\end{cases} & \epsilon_{j}= \begin{cases}1 \text { if } \tilde{y}_{j}=\tilde{y}_{j}^{0}, \\
0 \text { if } \tilde{y}_{j}<\tilde{y}_{j}^{0} .\end{cases} \tag{10.2}
\end{array}
$$

These quantities can all be calculated from the data available to the statistician: namely $x_{i}, \delta_{i}$ and $y_{j}, \epsilon_{j}$ for $i=1,2, \cdots, m, j=1,2, \cdots, n$, and the values of $z_{i}$ taken from a random number table. For instance, $\delta_{i}=1$ implies $x_{i}=$ $\min \left(x_{i}, z_{i}\right)$ and $\tilde{\delta}_{i}=1$, while $\delta_{i}=0$ implies $\tilde{x}_{i}=\min \left(x_{i}, z_{i}\right)$ and $\tilde{\delta}_{i}$ equals 1 or 0 as $z_{i}$ is less than or greater than $x_{i}$. The same considerations apply to $\tilde{y}_{j}$ and $\tilde{\epsilon}_{j}$.

The statistician is free to choose any convenient truncation distribution $D(s)$, and apply the $\hat{W}$ test to the modified data (10.2) instead of the original data (2.2), (2.3). The null hypothesis now becomes the equality of the distributions of $x_{i}^{0}$ and $\tilde{y}_{j}^{0}$, which are $\tilde{F}^{0}=D F^{0}$ and $\widetilde{G}^{0}=D G^{0}$, respectively. Applied to the tilde data, the $\hat{W}$ statistic is the maximum likelihood estimate of $P\left\{D F^{0} \geqq D G^{0}\right\}$, having that quantity as asymptotic expectation, and variance

$$
\begin{equation*}
\frac{1}{m+n}\left(\frac{1}{\lambda} \sigma_{1}^{2}+\frac{1}{1-\lambda} \sigma_{2}^{2}\right) \tag{10.3}
\end{equation*}
$$

where $\lambda=\lim m /(m+n)$, and

$$
\begin{align*}
& \sigma_{1}^{2}=\frac{1}{4} \int_{0}^{1} \frac{z^{2} d z}{H\left[\left(D F^{0}\right)^{-1}(z)\right]}, \\
& \sigma_{2}^{2}=\frac{1}{4} \int_{0}^{1} \frac{z^{2} d z}{I\left[\left(D F^{0}\right)^{-1}(z)\right]} \tag{10.4}
\end{align*}
$$

under $H_{0}$.
Suppose now we choose a $D(s)$ which is very nearly equal to

$$
D_{T}(s)=\left\{\begin{array}{l}
1 \text { if } s \leqq T  \tag{10.5}\\
0 \text { if } s>T
\end{array}\right.
$$

and denote the corresponding statistic by $\hat{W}_{T}$. Then we have as approximations,

$$
\begin{equation*}
E \hat{W}_{T}=\int_{-\infty}^{T} F^{0}(s) d G^{0}(s)+\frac{1}{2} F^{0}(T) G^{0}(T) \tag{10.6}
\end{equation*}
$$

and, under $H_{0}$,

$$
\begin{align*}
& \sigma_{1}^{2}=\frac{\left[F^{0}(T)\right]^{3}}{12 H(T)}+\frac{1}{4} \int_{F^{0}(T)}^{1} \frac{z^{2} d z}{H\left[F^{-1}(z)\right] d z}, \\
& \sigma_{2}^{2}=\frac{\left[F^{0}(T)\right]^{3}}{12 I(T)}+\frac{1}{4} \int_{F(T)}^{1} \frac{z^{2} d z}{I\left[F^{0^{-1}}(z)\right] d z} \tag{10.7}
\end{align*}
$$

By choosing $T$ sufficiently small, we can now avoid infinite values of $\sigma_{1}^{2}$ and $\sigma_{2}^{2}$.
Applying these results to the exponential case of section 9 , with $\alpha=1$, that is $F^{0}(s)=e^{-\phi s}, G^{0}(s)=e^{-\theta \phi s}, H(s)=I(s)=e^{-s}$, yields

$$
\begin{align*}
E \hat{W}_{T} & =\frac{\theta}{1+\theta}+\left(\frac{1}{2}-\frac{\theta}{1+\theta}\right) e^{-\phi(\theta+1) T}  \tag{10.8}\\
& =\frac{\theta}{1+\theta}+\left(\frac{1}{2}-\frac{\theta}{1+\theta}\right) t^{-(\theta+1)}
\end{align*}
$$

where we have defined $T=\phi^{-1} \log t$. Under $H_{0}: \theta=1$,

$$
\begin{equation*}
\sigma_{1}^{2}=\sigma_{2}^{2}=\frac{1}{12} \frac{\phi}{\phi-\frac{1}{3}}\left[1-\frac{1}{3 \phi} t^{-(3-1 / \phi)}\right] \tag{10.9}
\end{equation*}
$$

(Here we are excluding the case $\phi=1 / 3$.)
The efficacy of $\hat{W}_{T}$ is calculated to be

$$
\begin{equation*}
\operatorname{Eff}\left(\hat{W}_{T}\right)=\frac{3}{16} \frac{\phi-\frac{1}{3}}{\phi} r(t), \tag{10.10}
\end{equation*}
$$

where

$$
\begin{equation*}
r(t)=\frac{\left(1-t^{-2}\right)^{2}}{1-\frac{1}{3 \phi} t^{-(3-1 / \phi)}} \tag{10.11}
\end{equation*}
$$

The Pitman efficiency of the $\hat{W}_{T}$ test relative to the best parametric test is then

$$
\begin{equation*}
P_{\hat{W}_{T / M}}=\frac{3}{4} \frac{\left(\phi-\frac{1}{3}\right)(\phi+1)}{\phi^{2}} r(t) . \tag{10.12}
\end{equation*}
$$

Comparing this with

$$
\begin{equation*}
P_{\hat{W} / M}=\frac{3}{4} \frac{\left(\phi-\frac{1}{3}\right)(\phi+1)}{\phi^{2}} \tag{10.13}
\end{equation*}
$$

for $\phi>1 / 3$ (calculated from (9.8) with $\alpha=1$ ), shows that truncation can only lower the efficiency when $\phi \geqq 1$, for in this case $r(t) \leqq 1$ for all $t$. For $\phi<1$, an improvement in efficiency is possible by truncation at the correct point. The calculations for $\phi=1 / 2$ and $\phi=1 / 4$ are summarized in table III.

TABLE III
Optimum Truncation Point and Relative Pitman Efficiency
Calculated for $\phi=1 / 2$ and $1 / 4$

|  | $\phi=1 / 2$ | $\phi=1 / 4$ |
| :--- | :---: | :---: |
| Optimum truncation point $T$ | 3.38 | 2.43 |
| Relative truncation point $T$ | 1.69 | 0.61 |
| $P \hat{W}_{T} / M$ | 0.798 | 0.427 |
| $P \hat{W} / M$ | 0.750 | 0.000 |

It should be noted that for $\phi=1 / 4$, the greatest power is achieved at the expense of a really drastic truncation, at 61 per cent of the expectation $1 / \phi$. A more reasonable procedure, which has not been investigated by the author, is to combine the $\hat{W}$ and $W_{G}$ tests in those cases where censorship is so severe, say greater than $2 / 3$ of the observations, that the $\hat{W}$ test alone may be unstable. This could be done by using the $\hat{Q}\left(x_{i}, y_{j}, \delta_{i}, \epsilon_{j}\right)$ scoring function in table II for those cases where either $x_{i}$ or $y_{j}$ is smaller than a threshold $T$, and the scoring function $Q_{G}$, given by (3.3), in all other cases.

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